

AMENDMENTS TO THE CLAIMS:

The listing of claims will replace all prior versions, and listings of claims in the application:

LISTING OF CLAIMS:

1. (Original) A system for producing an actuator response, the system comprising
a plurality of rows of actuators capable of producing an actuator response in
reply to an control signal;
a resistive strip connected to the plurality of rows of actuators; and
a first electrode having a first voltage connected to the resistive strip and a
second electrode having a second voltage connected to the resistive strip for
transmitting the control signal to the rows of actuators to thereby cause the rows of
actuators to produce the actuator response.
2. (Original) The system of claim 1, wherein the plurality of rows of actuators
produce the
actuator response that depends on a locally computed value of a function of the control
signal.
3. (Original) The system of claim 1, wherein the length of the resistive strip is
substantially equal to a correlation length in which each row in the plurality of rows is
correlated to every other row in the plurality of rows.
4. (Original) The system of claim 3, wherein the first electrode is connected to a first
end of the resistive strip, and the second electrode is connected to a second end of the
resistive strip.
5. (Original) The system of claim 4, wherein the first voltage has a value V_1 and the
second voltage has a value V_2 such that $(V_1 + V_2)/2$ is chosen to approximate a desired
actuation profile.

6. (Original) The system of claim 5, wherein $(V_1 + V_2)/2$ is chosen to substantially equal an average value of the desired actuation profile over a position substantially equal to a location of the resistive strip.
7. (Original) The system of claim 1, wherein the first voltage has a value V_1 and the second voltage has a value V_2 such that $(V_1 - V_2)$ is chosen to approximate a desired actuation profile.
8. (Original) The system of claim 7, wherein $(V_1 - V_2)$ is chosen to substantially equal an average slope of the desired actuation profile over a position substantially equal to a location of the resistive strip.
9. (Currently amended) A system for producing an actuator response, the system comprising
- a plurality of rows of actuators capable of producing an actuator response in reply to a control signal;
 - a resistive strip connected to the plurality of rows of actuators; and
 - N electrodes, where N is an integer greater than one, having a voltage V_1, \dots, V_N , each electrode being connected to the resistive strip to transmit the control signal to the rows of actuators to thereby cause the rows of actuators to produce the actuator response, wherein a particular one of the N electrodes is allowed to float, thereby increasing a correlation region.
10. (Original) The system of claim 9, such that the distance between any two adjacent electrodes is substantially equal to a correlation length of the plurality of rows of actuators.
11. (Original) The system of claim 9, wherein $(V_j + V_{j+1})/2$, for each j satisfying $1 \leq j \leq N-1$, is chosen to approximate a desired actuation profile.

12. (Original) The system of claim 11, wherein $(V_j + V_{j+1})/2$ is chosen to substantially equal an average value of the desired actuation profile over a position substantially equal to a location of the portion of the resistive strip between the j th and $j+1$ electrodes.
13. (Original) The system of claim 9, wherein $(V_j - V_{j+1})$, for each j satisfying $1 \leq j \leq N-1$, is chosen to approximate a desired actuation profile voltage.
14. (Original) The system of claim 13, wherein $(V_j - V_{j+1})$ is chosen to substantially equal an average slope of the desired actuation profile over a position substantially equal to a location of the portion of the resistive strip between the j th and $j+1$ electrodes.
15. (Original) The system of claim 9, wherein each of the plurality of rows of actuators can produce two discrete actuator responses.
16. (Canceled)
17. (Currently amended) A system for producing an actuator response, the system comprising
a resistive sheet;
an array of actuators electrically connected to said resistive sheets via contacts;
and
a plurality of electrodes for fixing voltages on the resistive sheet, wherein by varying the voltages a desired actuation profile can be produced by the array of actuators to produce the actuator response; and
a capacitive layer coupled to the resistive sheet to allow a correlation region to depend on time.
18. (Original) The system of claim 17, wherein the plurality of electrodes includes at least four electrodes for fixing voltages, V_1, \dots, V_4 on the resistive sheet, wherein by

varying the voltages V_1, \dots, V_4 a desired actuation profile can be produced by the array of actuators to produce the actuator response.

19. (Original) The system of claim 18, wherein, if the four voltages lie substantially at points (0,0), (1,0), (0,1) and (1,1) of a Cartesian coordinate system, the desired actuation profile, expressed as voltage $V(x,y)$ as a function of position within a square having corners at said points, is given substantially by

$$V(x,y) = V_3(1-x)(1-y) + V_1(1-x)y + V_4x(1-y) + V_2xy.$$

20. (Canceled)

21. (Currently amended) A method for producing a non-electrical an-actuator response, the method comprising

electrically connecting a plurality of rows of actuators to a resistive strip, said actuators capable of producing a non-electrical an-actuator response in reply to aan electrical control signal;

applying a first voltage to the resistive strip via a first electrode; and

applying a second voltage to the resistive strip via a second electrode, wherein the application of said first voltage and said second voltage provides the electrical control signal that causes the actuators to produce the non-electrical actuator response.

22. (Original) The method of claim 21, wherein, in the step of electrically connecting, the length of the resistive strip is substantially equal to a correlation length in which each row in the plurality of rows is correlated to every other row in the plurality of rows.

23. (Original) The method of claim 21, wherein, in the step of applying a first voltage and applying a second voltage, the first voltage has a value V_1 and the second voltage has a value V_2 such that $(V_1 + V_2)/2$ is chosen to approximate a desired actuation profile.

24. (Original) The method of claim 23, wherein, in the step of applying a first voltage and applying a second voltage, $(V_1 + V_2)/2$ is chosen to substantially equal an average value of the desired actuation profile over a position substantially equal to a location of the resistive strip.
25. (Original) The method of claim 21, wherein, in the step of applying a first voltage and applying a second voltage, the first voltage has a value V_1 and the second voltage has a value V_2 such that $(V_1 - V_2)$ is chosen to approximate a desired actuation profile.
26. (Original) The method of claim 25, wherein, in the step of applying a first voltage and applying a second voltage, $(V_1 - V_2)$ is chosen to substantially equal an average slope of the desired actuation profile over a position substantially equal to a location of the resistive strip.
27. (New) The system of claim 1, wherein the actuator response is a non-electrical response and the control signal is an electrical control signal.
28. (New) The system of claim 1, wherein the plurality of rows are configured to be in permanent contact with the resistive strip.